### A SPICE benchmark for global tomographic methods and

### **Test of Global tomographic models**

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Lapo Boschi and Thorsten Becker



## Part I

## Why we do the Benchmark?

### Factors affecting the results of seismic tomography

- Approximation of forward computation
- Ray coverage
- Correlation length
- grid size
- Damping coefficients
- How the different datasets are weighted?
- Sensitivity kernel is 1D, 2D or 3D
- Selection of starting reference model?

#### **Multi-solution of seismic inversion**

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## Part I

- Objectives of Benchmark
- 1. understand the resolving properties of specific imaging algorithms
- 2. how current imaging techniques are limited by approximations in theory and by the data quality and coverage.

## Procedure of Benchmark

**1.Preliminary Benchmark:** To make sure that the computation precision, acquisition geometry, data format, sampling rate are good for tomography test

- Minimum period 50s
- Simple isotropic model
- No topography, ocean, ellipticity

### 2. Benchmark

- Minimum period 32s
- Complex anisotropic model (designed by *Valerie Maupin*)
- With gravity, topography, ocean, ellipticity
- Constant Moho interface
- Use spectral element method (SEM)

## 3. Procedure





### Source and station distribution of preliminary benchmark



#### 27 Events distribution



256 stations distribution



Inversion results using Automated Multi-mode inversion of surface and S waveforms by Sergei Lebedev (Lebedev, et al., 2005).

### **Preliminary Benchmark**

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### Source and station distribution of second benchmark



256 stations distribution



29 Events distribution (magnitude is more homogeneous)

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### Inversion of Second Benchmark dataset

- 1. Automated multimode Inverison (AMI) (Sergei Lebedev)
- 2. Phase-velocity measurement + regionalization+depth inversion (already know the input model)
- (1). use Roller-Coaster method to calculate the phase velocity for each source-receiver path (Beucler, et al., 2003)
- (2). use CLASH method to calculate the anisotropic phase velocity distribution for different period (Beucler and Montagner, 2006)
- (3). 1D Depth inversion (11 periods from 45s to 315s)

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#### **Input models**



shear velocity variation from 1-D +6% -6% Depth= 70 km



shear velocity variation from 1-D +6% -6% Depth= 160km



shear velocity variation from 1-D +6% Depth= 300 km

-6%



shear velocity variation from 1-D

**Output model of AMI** by Sergei Lebedev (only isotropic)

70km

160km

300km

520km

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+6% Depth= 161 km



shear velocity variation from 1-D +6% Depth= 302 km

-6%



Depth= 520 km



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shear velocity variation from 1-D -6% +6% 

Depth=71 km



shear velocity variation from 1-D -5% +5%

Depth= 65 km

shear velocity variation from 1-D

Depth= 164 km

shear velocity variation from 1-D

Depth= 302 km

**CLASH** 

+5%

+3%

-5%

-3%







shear velocity variation from 1-D +6% -6% 

Depth= 160km



+6% -6% Depth= 300 km Input model



shear velocity variation from 1-D -6% +6% 

Depth= 161 km





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## **Third Benchmark (going on)**

- use Moho topograhy
- Array surface-wave tomography (spacing 70km)
- Increase global station density
- 2D crustal velocity
- Variation of azimuthal anisotropy
- Minimum period 32s



Global station coverage (spacing 500km)



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## Part II

### **Test of Global tomographic model**

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Data are not to be used to create a model, but, instead, to falsify models.

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Albert Tarantola (Nature, 2006)

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## **Objectives**

• how well different tomographic models can explain the overtones and fundamental modes of surface waves.



Correlation coefficients: x1= 0.9817 R1= 0.9791 X2= 0.7715 R2= 0.9075

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## **Configuration of Test**

- Minimum period is 100s
- •Use Deep events with magnitude (Mw) is about 7
- •The duration of events is less than 20s
- •Length of traces is 10500s (Include R2, L2)
- •Three components (LHZ, LHR,LHT)
- •Currently tested model: S20RTS, SAW24B16, SB4L18, Smean and Princeton-05

## **Currently tested models**

•S20RTS: derived by inverting Rayleigh wave dispersion , body-wave Travel time, and normal-mode Splitting data

•SAW24B16: derived with handpicked transverse component waveforms,

• SB4L18: Scripps "high-resolution" model. Derived from surface wave phase velocity, free oscillation structure coefficients and long-period body wave absolute and differential travel times.

•Smean: average of S20RTS, SAW24B16, and SB4L18

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• Princeton-05: derived using finite-frequency tomography of body waves

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#### Comparison of different models at depth of 150km

![](_page_17_Figure_1.jpeg)

## **Numerical computation**

- •Coupling SEM method (Capdeville et al., 2003)
- Average CRUST2.0 for anti-aliasing
- •1D anisotropic PREM model as reference model
- •incoporate the Moho topography

•The variation of Vp and density is scaled to perturbations of Vs by factor 0.5 and 0.4

### **Event I**

![](_page_19_Figure_1.jpeg)

![](_page_19_Figure_2.jpeg)

LHZ

![](_page_19_Figure_4.jpeg)

#### China.Russia Border event

Depth=645km

![](_page_19_Figure_7.jpeg)

LHT

Path coverage for different component

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![](_page_20_Figure_0.jpeg)

![](_page_21_Figure_0.jpeg)

	Smean	S20RTS	SAW24B16	SB4L18	Princeton-05	PREM	
X1	0.956	0.949	0.910	0.942	0.911	0.825	
R1	0.918	0.943	0.927	0.889	0.865	0.770	
X2	0.864	0.850	0.833	0.837	0.736	0.705	
R2	0.808	0.842	0.820	0.806	0.220	0.530	

LHZ: 59 traces

	Smean	S20RTS	SAW24B16	SB4L18	Princeton-05	PREM	
G1	0.964	0.964	0.948	0.965	0.939	0.912	LHT :total 25 traces
L1	0.968	0.956	0.943	0.945	0.872	0.793	
G2	0.890	0.888	0.870	0.877	0.756	0.735	
L2	0.915	0.799	0.842	0.888	0.5684	0.416	

	Smean	S20RTS	SAW24B16	SB4L18	Princeton-05	PREM	
X1	0.911	0.906	0.899	0.896	0.881	0.832	I HR: total 25 traces
R1	0.900	0.917	0.914	0.868	0.866	0.788	
X2	0.782	0.770	0.759	0.763	0.641	0.551	
R2	0.863	0.8716	0.818	0.852	0.185	0.402	

#### **Average Correlation coefficients for Event China.Border**

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## **Event II**

![](_page_23_Figure_1.jpeg)

LHZ (76 traces)

![](_page_23_Figure_3.jpeg)

LHT (20 traces)

Event: Brazil, 2003

Depth: 556km

![](_page_23_Figure_7.jpeg)

LHR (25 traces)

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	Smean	S20RTS	SAW24B16	SB4L18	PREM
X1	0.948	0.942	0.935	0.937	0.8334
R1	0.919	0.950	0.934	0.868	0.7430
X2	0.848	0.836	0.783	0.820	0.646
R2 ,	0.797	0.874	0.810	0.784	0.581

#### 76 traces

	Smean	S20RTS	SAW24B16	SB4L18	PREM
X1	0.95	0.953	0.958	0.956	0.9123
R1	0.892	0.928	0.902	0.845	0.7800
X2	0.852	0.859	0.842	0.838	0.6881
R2	0.821	0.861	0.870	0.801	0.5883

25 traces

	Smean	S20RTS	SAW24B16	SB4L18	PREM
X1	0.877	0.872	0.881	0.884	0.828
R1	0.955	0.939	0.917	0.932	0.802
X2	0.762	0.756	0.712	0.725	0.651
R2 ,	0.890	0.893	0.774	0.854	0.454

20 traces

#### Average correlation coefficients

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## Perspective

#### 1. Try more deep earthquakes

- Magnitude Mw between 7.1 and 7.5
- Source depth >500km
- Duration <20s

![](_page_25_Figure_5.jpeg)

Distribution of deep earthqukes (from Harvard CMT)

#### 2. Try more models

- geodynamic models
- Recent new models

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## **Preliminary Conclusions**

- Correlation coefficients of X1 (G1) and R1 (L1) are higher than X2 (G2) and R2 (L2)
- for **Smean, S20RTS, SAW24B16, SB4L18**, the correlation coefficients have no obvious difference
- 3D models have better waveform fitting than anisotropic **PREM**

![](_page_27_Picture_0.jpeg)

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![](_page_28_Figure_0.jpeg)

Depth Inversion using 11 periods: 45s, 55s, 68s, 84s, 103s, 127s, 156s, 192s, 220s, 240s, 273s.

![](_page_29_Figure_0.jpeg)

# Depth Inversion using 11 periods: 45s, 55s, 68s, 84s, 103s, 127s, 156s, 192s, 220s, 240s, 273s.

![](_page_30_Figure_0.jpeg)